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## A SIMPLE TRICK ENHANCES L5991's STANDBY FUNCTION

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#### Abstract

This application notes describes a simple technique that allows improving the Standby function of the advanced PWM controller L5991. The price to pay for that is the addition of just two resistors and two diodes, but the benefit brought in terms of no-load consumption in mains-operated converters is worth this small fee. The effectiveness of the improved Standby function will be proved and assessed on a couple of existing designs.


## Introduction

L5991's Standby function is a valuable help in reducing light-load input consumption of offline converters and making them compliant with energy saving standards such as EnergyStar, Energy2000 and others. This function, optimized for flyback topology, is the ability of automatically - and abruptly - reducing the oscillator frequency (i.e. converter's switching frequency) as the converter's load falls below a defined threshold and restoring the normal oscillator frequency as the load increases and exceeds a second threshold.
The frequency shift allows minimizing power losses related to switching frequency, which represent most of losses at light or no load, without giving up the advantages of a higher switching frequency at full load.
Being the L5991 a current-mode controller [1], the output voltage (VCOMP) of its error amplifier (pin 6, COMP), except for an offset, is proportional to the peak primary current and then to the energy handled by the transformer cycle by cycle. It is then possible to deduce converter's load conditions by monitoring VCOMP.

Figure 1. L5991's Standby function operation: $\mathrm{f}_{\mathrm{sw}}$ vs. $\mathrm{V}_{\mathrm{COMP}}$ locus (left) and $\mathrm{V}_{\mathrm{COMP}}$ vs. $\mathrm{P}_{\text {in }}$ locus (right).


If the peak primary current decreases as a result of a decrease of the power demanded by the load and $\mathrm{V}_{\text {COMP }}$ falls below a fixed threshold ( $\mathrm{V}_{\mathrm{T} 1}$ ), the oscillator frequency will be set at a lower value (fsB). If now the peak primary current increases and $\mathrm{V}_{\text {COMP }}$ exceeds a second threshold $\left(\mathrm{V}_{\mathrm{T} 2}>\mathrm{V}_{\mathrm{T} 1}\right)$ the oscillator frequency will be reset at the normal value (fosc). Since the frequency shift causes $\mathrm{V}_{\text {comp }}$ to shift too but in the opposite direction for energy balance reasons, an appropriate hysteresis $\left(\mathrm{V}_{\mathrm{T} 2}-\mathrm{V}_{\mathrm{T} 1}\right)$ is provided to prevent the oscillator frequency from switching back and forth between fSB and fosc. This operation is shown in fig. 1.
The L5991 allows programming both the normal and the standby frequency. $\mathrm{V}_{\mathrm{T} 1}$ and $\mathrm{V}_{\mathrm{T} 2}$ are internally fixed but

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it is possible to adjust the thresholds in terms of input power level (PNO, PSB) by adding a DC offset on its current sense input (pin 13, ISEN). Reference [2] provides plenty of details on this function and its usage.
There is a maximum abrupt frequency shift allowed, which is related to the amount of hysteresis: the theoretical maximum ratio of $f_{\text {osc }}$ to fSB is 5.59 , however this value does not account for the dynamic changes of $\mathrm{V}_{\mathrm{COMP}}$ during the transients resulting from the frequency shift. As a matter of fact, depending on the closed-loop characteristics of the voltage control loop and on the amplitude of the load change that causes the frequency shift, $V_{\text {COMP }}$ may overshoot or undershoot before reaching its new steady-state value (see figure 1). If during a transient the other threshold is crossed, VCOMP may bounce from one threshold to the other and the switching frequency be unstable, going back and forth from one value to the other. As a result, the practical limit is less than the theoretical value, probably less than 4 and, at any rate, the control loop dynamics needs to be kept relatively slow to limit the aptitude of VCOMP to under- or overshooting.
In [2] it is explained also that the addition of a DC offset on the current sense pin increases the maximum bsc to fsB ratio allowed. However, this technique is suitable for allowing a higher fosc with a given fsB. The lower limit on $\mathrm{f}_{\mathrm{SB}}$ is determined by other considerations: if it is in the audible range ( $<16 \mathrm{kHz}$ ), the transformer will very likely generate audible noise, especially at power levels where the frequency is about to shift back to fosc, because of the high peak current involved.
Often, instead, for a given fosc an fSB as low as possible would be required to meet the latest design targets aimed at complying even with the most severe energy saving standards. In this case it would be desirable to have a very low frequency under no-load conditions, where the peak current is too small to be able to generate audible noise, and a frequency above the audible range at power levels where audible noise issues may arise. This is exactly the purpose of the modification to the oscillator proposed in the following section.

## Standby function improvement

To realize the aforementioned function, the oscillator frequency needs to be dependent on converter's load conditions - the lower the load, the lower the frequency and vice versa - and only when this is useful, that is at light load. This can be done by adding few parts to the oscillator of the L5991, as shown in figure 2.
Assuming a perfect matching of the two diodes (with a common-cathode dual diode like the BAV70 this is closer to reality), when VCOMP falls below 3 V (oscillator's peak voltage) some of the current that charges CT is diverted to ground through $\mathrm{R}_{\mathrm{C}}$, D 1 an $\mathrm{R}^{\prime}$. In this way the rate of rise of the voltage across $\mathrm{C} T$ is slowed down and the oscillator frequency decreased, the lower $\mathrm{V}_{\text {COMP }}$ the lower the frequency. Instead, when $\mathrm{V}_{\mathrm{COMP}}$ is greater than 3V D1 isolates Rc and the oscillator frequency will be either fosc or fsB, like in the standard L5991 oscillator circuit. $\mathrm{R}_{\mathrm{A}}, \mathrm{R}_{\mathrm{B}}$ and $\mathrm{C}_{\top}$ can be then calculated as usual with the formulae given in [1]; as to the determination of $\mathrm{R}_{\mathrm{C}}$ and R' please refer to the appendix.

Figure 2. Oscillator modification to improve Standby function


D2 compensates for the temperature shift of the forward voltage drop $V_{F}$ of $D 1$. Considering that the current flowing through the diodes is in the hundred $\mu \mathrm{A}$ or less, D1 and D2 dissipate negligible power and only ambient temperature affects their $\mathrm{V}_{\mathrm{F}}$. Assuming D1 and D2 match perfectly, neither oscillator frequency nor the point where $R_{C}$ comes into play will depend on ambient temperature. In real-world operation, considering also that D1 and D2 do not usually carry the same current, a minimum temperature effect can be observed.

The "frequency foldback" provided by the additional circuit starts in the neighborhood of $\mathrm{V}_{\mathrm{COMP}}=3 \mathrm{~V}$, that is a little before that the high-to-low frequency shift takes place. After the shift, $\mathrm{V}_{\text {COMP }}$ will be higher and then the switching frequency will be close or exactly equal to fSB, depending on the fosc to fSB ratio.
In applications where the switching frequency needs not be tightly fixed for some specific reason there is no major drawback to this technique. The only point to take care of is that the oscillator frequency be in the audible range only when the peak current is so low that no sound may come from the transformer, even when it is made with normal construction techniques. This can be obtained simply by choosing fSB well above the audible range (e.g. fSB $>30 \mathrm{kHz}$ seems to be a good rule of thumb).

The benefits, on the contrary, are considerable:

1) Very low switching frequencies are possible which, as already stated, will allow treating the power throughput as much efficiently as possible: MOSFET's capacitive losses, gate drive consumption and other parasitic losses will be minimized. See [2] for more details on them.
2) Since the additional components will be concerned with taking the oscillator frequency to very low values, the standby frequencyfsB can be kept relatively high, thus reducing the abrupt frequency shift and eliminating the need for a slow feedback to prevent frequency instability. As already said, keeping $\mathrm{f}_{\mathrm{SB}}$ high has the positive side-effect of eliminating audible noise issues.
3) As a result of the faster dynamic response, start-up under no-load conditions is possible even with a minimum pre-load on the output. The dummy load represented by the feedback network, as well as bleeders, if used, can be minimized. The limit to the dummy load reduction is given by the collapse that the voltage delivered by the self-supply winding experiences with no load, which must not pull the supply voltage of the L5991 below the UVLO threshold.
To evaluate how much this function modification improves converter's performance at light or no load, the 45W wide-range mains AC-DC adapter illustrated in [3] and the 80W power-factor-corrected AC-DC adapter described in [4] will be optimized following the guidelines revealed by the above considerations. The "European Code of Conduct on Efficiency of External Power Supplies", ECC in short, whose limits are summarized in table 1, will be assumed as the reference.

Table 1. Limits envisaged by European Code of Conduct on Efficiency of External Power Supplies

| Rated Input Power | Max. no-load Power Consumption |  |  |
| :---: | :---: | :---: | :---: |
|  | Phase 1 <br> $\mathbf{0 1 . 0 1 . 2 0 0 1}$ | Phase 2 <br> $\mathbf{0 1 . 0 1 . 2 0 0 3}$ | Phase 3 <br> $\mathbf{0 1 . 0 1 . 2 0 0 5}$ |
| $\geq 0.3 \mathrm{~W}$ and $<15 \mathrm{~W}$ | 1.0 W | 0.75 W | 0.30 W |
| $\geq 15 \mathrm{~W}$ and $<50 \mathrm{~W}$ | 1.0 W | 0.75 W | 0.50 W |
| $\geq 50 \mathrm{~W}$ and $<75 \mathrm{~W}$ | 1.0 W | 0.75 W | 0.75 W |

Optimization of a 45W, wide-range mains AC-DC adapter
For reader's convenience, table 2 summarizes the electrical spec of the adapter under consideration. Please refer to [3] for a detailed description and full evaluation data.
Table 2. 45W, wide-range mains AC-DC adapter: electrical specification of the original design

| Input Voltage Range ( $\mathrm{V}_{\text {in }}$ ) | 88 to 264 Vac |
| :--- | :--- |
| Mains Frequency (fL) | $50 / 60 \mathrm{~Hz}$ |
| Maximum Output Power (Pout) | 45 W |
| Output | Vout $=18 \mathrm{~V} \pm 3 \%$ |
|  | lout $=2.5 \mathrm{~A} \mathrm{max}$. |
|  | Full load ripple $\leq 2 \% \mathrm{pk}-\mathrm{pk}$ |
| Normal Operation Switching Frequency (fosc) | 70 kHz typ. |
| Light Load Switching Frequency (fsB) | 18 kHz typ. |
| Full-load Efficiency (@ Pout $=45 \mathrm{~W}, \mathrm{Vin}=88 \div 264 \mathrm{Vac})$ | $>80 \%$ |
| Maximum no-load Input Power (Vin $=88 \div 264 \mathrm{Vac})$ | $<1 \mathrm{~W}$ |

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Since the full-load input power is greater than 50W, this adapter belongs to the third bracket envisaged by the ECC. Its no load consumption is $0.9 \mathrm{~W} @ 264 \mathrm{Vac}$ and $0.7 \mathrm{~W} @ 220 \mathrm{Vac}$ then it meets Phase 1 limit (1W) and is close to that of Phase 2 and 3 ( 0.75 W ) with almost no margin.
Although the ECC specifies that the compliance test be done at the nominal voltage 230 Vac , in the pre-compliance test it is quite usual to refer to the consumption at 264 Vac , to account for production spread. With this criterion the adapter cannot be considered compliant with Phase 2 or 3 limits.
The target of the optimization is then to make the adapter ECC-compliant in the above mentioned sense. Figure 3 shows the electrical schematic of the converter with the added and modified components highlighted. Only these changes will be discussed.

Figure 3. 45W AC-DC adapter: electrical schematic of the modified circuit


1) The oscillator has been modified to maintain the same frequency under normal operation $(70 \mathrm{kHz})$ at full load and have a standby frequency equal to half the normal frequency ( 35 kHz ). The oscillator frequency with no-load will be 5 kHz . Further details on the calculations can be found in the appendix.
2) The dummy load represented by the feedback components on the secondary side $(170 \mathrm{~mW}$ in the original design) has been reduced at 40 mW : R21 has been increased from $348 \Omega$ to $3.16 \mathrm{k} \Omega$ and, consequently, R18 from 2.2 to $20 k$ to maintain the same regulated output voltage. This reduces the current consumption of the divider from 7.2 to 0.8 mA . Additionally, R19 which was to provide 1 mA extra bias current to the reference of the PC905, has been taken out since it was not strictly necessary.
3) The frequency compensation of the voltage control loop (C7, C14, R20) has been modified so as to get a larger bandwidth - it has been almost doubled - and then a faster response. The main purpose of that is to allow a correct start-up of the converter even with no load, whereas a slow feedback (basically, a large C14) causes the system to try continuously to restart under these conditions.
4) R7 has been decreased from 4.7 to $1 \Omega$, to prevent the supply voltage of the L5991 from going below the UVLO threshold with no load. To help this, the total consumption of the IC has been reduced by 0.3 mA by increasing R8 and R9 (from 5.6 to $22 \mathrm{k} \Omega$ and from 6.8 to $27 \mathrm{k} \Omega$, respectively). Although with this change the voltage generated at full load is higher, it is still below the OVP threshold, set by R5 and R6, with a safe margin.
These modifications are summarized in table 3.

Table 3. 45W, wide-range mains AC-DC adapter: list of modifications to the original design

| Part | Original value | New Value | Part | Original value | New Value |
| :---: | :---: | :---: | :---: | :---: | :---: |
| R 7 | $4.7 \Omega$ | $1 \Omega$ | R 20 | $5.6 \mathrm{k} \Omega$ | $180 \mathrm{k} \Omega$ |
| R 8 | $5.6 \mathrm{k} \Omega$ | $22 \mathrm{k} \Omega$ | R 21 | $348 \Omega$ | $3.16 \mathrm{k} \Omega$ |
| R 19 | $6.8 \mathrm{k} \Omega$ | $27 \mathrm{k} \Omega$ | $\mathrm{R}_{\mathrm{C}}$ | --- | $5.9 \mathrm{k} \Omega$ |
| R 12 | $24 \mathrm{k} \Omega$ | $12 \mathrm{k} \Omega$ | R | --- | $8.2 \mathrm{k} \Omega$ |
| R 13 | $8.2 \mathrm{k} \Omega$ | $12 \mathrm{k} \Omega$ | C 7 | 220 pF | 3.3 nF |
| R 18 | $2.2 \mathrm{k} \Omega$ | $20 \mathrm{k} \Omega$ | C 14 | 470 nF | 4.7 nF |
| R 19 | $1.2 \mathrm{k} \Omega$ | ----- | 1 N 4148 |  |  |

## 45W AC-DC adapter: evaluation results

The following diagrams compare the performance of the original design ("standard standby") with that of the modified one ("improved standby"). For reference, it has also been measured the input consumption after replacing the start-up circuit made up of R1, R2 and D3 with an active start-up circuit (see fig. 12).
To be noted in figure 4, the no-load consumption is $<0.6 \mathrm{~W} @ 264 \mathrm{Vac}$, then the adapter under test meets the ECC limits, Phase 3 ( $<0.75 \mathrm{~W} @ 230 \mathrm{Vac}$ ) with some margin even without the use of an active start-up circuit.

Figure 4. 45W AC-DC adapter: light load input consumption comparison


The diagram on the left in figure 5 shows the relationship between output current and switching frequency obtained with the modified oscillator. The oscillator frequency is not much affected by the input voltage, as shown also by the oscilloscope diagrams of figures 6 to 10: the internal propagation delay of the current sense pin is compensated by R3 and R4, then the changes of $\mathrm{V}_{\mathrm{COMP}}$ (and, consequently, $\mathrm{f}_{\mathrm{sw}}$ ) with the input voltage are negligible.
The diagram on the right in figure 5 illustrates the effect of temperature on both the oscillator frequency and the no-load input consumption (@264Vac) in the temperature range $0-70^{\circ} \mathrm{C}$ : the variation is very limited.

Figure 5. 45W AC-DC adapter: $\mathrm{f}_{\mathrm{sw}}$ vs. $\mathrm{l}_{\mathrm{out}}($ left $) ; \mathrm{P}_{\mathrm{in}}\left(@ \mathrm{P}_{\mathrm{out}}=0\right.$ ) and $\mathrm{f}_{\mathrm{sw}}$ vs. ambient temperature (right)


Figure 6. 45W AC-DC adapter: waveforms @ Pout $=45 \mathrm{~W}$


Figure 7. 45W AC-DC adapter: waveforms @ $P_{\text {out }}=7 \mathrm{~W}$, just after the abrupt frequency shift


Figure 8. 45W AC-DC adapter: waveforms @ Pout = 0.5W


Figure 9. 45W AC-DC adapter: waveforms @ Pout = 0.3W


Figure 10. 45W AC-DC adapter: waveforms @ Pout = OW


Figure 11. 45W AC-DC adapter: load transient $0.1 \Leftrightarrow 2.5 \mathrm{~A} @ 220 \mathrm{Vac}$


Optimization of a 80W AC-DC adapter with PFC
Table 4 summarizes the items of the electrical spec of this adapter more relevant to this context. Please refer to [4] for full electrical spec and evaluation data, as well as for a detailed description.

Table 4. 80W AC-DC adapter with PFC: electrical specification of the original design

| Input Voltage Range (Vin) | 90 to 265 Vac |
| :--- | :---: |
| Mains Frequency (fL) | $50 / 60 \mathrm{~Hz}$ |
| Maximum Output Power (Poutmax) | 80 W |
| Output | $\mathrm{V}_{\text {out }}=18 \mathrm{Vdc} \pm 2 \%$ <br> $\mathrm{I}_{\text {out }}=0$ to 4.5 A <br> $\mathrm{~V}_{\text {ripple }} \leq 1 \%$ |
| Line and Load regulation | $<1 \%$ |
| Switching Frequency (Flyback, @ Pout $=80 \mathrm{~W})$ | 65 kHz |
| Switching Frequency (Flyback, @ $\mathrm{P}_{\text {out }}=0 \mathrm{~W}$ ) | 20 kHz |
| Target Overall Efficiency (@ $\mathrm{P}_{\text {out }}=80 \mathrm{~W}, \mathrm{~V}_{\text {in }}=90 \div 265 \mathrm{Vac}$ ) | $\eta>75 \%$ |
| Maximum No-load Input Power $\left(\mathrm{V}_{\text {in }}=90 \div 265 \mathrm{Vac}\right)$ | $<1 \mathrm{~W}$ |

The full-load input power is greater than 100W, then this adapter is actually out of the scope of the ECC. Its no load consumption ( $0.9 \mathrm{~W} @ 265 \mathrm{Vac}, 0.7 \mathrm{~W} @ 220 \mathrm{Vac}$ ), however, is within the Phase 1 limit ( 1 W ) and not far from that of Phase 2 and $3(0.75 \mathrm{~W} @ 230 \mathrm{Vac})$ for the highest power bracket.
Again, the target of the optimization is to meet Phase 3 limit @Vin = 264 Vac. Figure 12 shows the electrical schematic with the added and modified components highlighted. Only these changes, which track those made in the previously considered design plus those related to the PFC stage, will be discussed

Figure 12. 80W AC-DC adapter with PFC: electrical schematic of the modified circuit


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1 The oscillator of the L5991 has been modified to maintain the same frequency under normal operation ( 65 kHz ) at full load and have a standby frequency of 36 kHz . Also in this case the oscillator frequency with no-load is chosen 5 kHz . Further details on the calculations can be found in the appendix.
2 Again, the dummy load represented by the feedback components on the secondary side has been reduced at about 40 mW (see the same point of the previous design).
3 The frequency compensation of the voltage control loop (C7, C14, R20) has been modified so as to double the bandwidth and get a faster response (especially useful at start-up).
4 R28 has been decreased from 3.3 to $1 \Omega$, to prevent the supply voltage of the L5991A from going below the UVLO threshold with no load, while not exceeding the rating of both the L5991A and the L6561.
5 The multiplier bias resistors ( $\mathrm{R} 3 \mathrm{~A}=\mathrm{R} 3 \mathrm{~B}=680 \mathrm{k} \Omega$ and $\mathrm{R} 1=10 \mathrm{k} \Omega$ ) of the L 6561 consume 103 mW $@ 264 \mathrm{Vac}$, then their value has been more than doubled $(R 3 A=R 3 B=1.5 \mathrm{M} 2$ and $R 1=22 \mathrm{k} \Omega)$. In this way their maximum consumption is reduced at 46 mW @ 264 Vac.
6 The output divider of the PFC pre-regulator ( $\mathrm{R7A}=\mathrm{R} 7 \mathrm{~B}=499 \mathrm{k}$ 2 and $\mathrm{R} 1=6.34 \mathrm{k} \Omega$ ) gives origin to a consumption of $140 \mathrm{~mW} @ 264 \mathrm{Vac}$. With the aim of reducing the consumption at 40 mW maximum, while not degrading the dynamic OVP function, the feedback network has been modified as shown in figure 13. The capacitor bypasses the two $1.5 \mathrm{M} \Omega$ resistors during output voltage overshoots, resulting in a only slightly higher OVP threshold, as compared to the original one. The positive sideeffect is an improvement of the transient response of the PFC pre-regulator. The components for the frequency compensation of the error amplifier of the L6561 have been changed consequently.
The modifications are summarized in table 5 .
Figure 13. Modified PFC pre-regulator's feedback and frequency compensation network


Table 5. 80W AC-DC adapter with PFC: list of modifications to the original design

| Part | Original value | New Value | Part | Original value | New Value |
| :---: | :---: | :---: | :---: | :---: | :---: |
| R1 | $10 \mathrm{k} \Omega$ | $22 \mathrm{k} \Omega$ | R 31 | $2.2 \mathrm{k} \Omega$ | $20 \mathrm{k} \Omega$ |
| $\mathrm{R} 3 \mathrm{~A}, \mathrm{R} 3 \mathrm{~B}$ | $680 \mathrm{k} \Omega$ | $1.5 \mathrm{M} \Omega$ | R 33 | $13 \mathrm{k} \Omega$ | $33 \mathrm{k} \Omega$ |
| R 6 A | $6.34 \mathrm{k} \Omega$ | $22 \mathrm{k} \Omega$ | R 34 | $510 \mathrm{k} \Omega$ | --- |
| $\mathrm{R} 7 \mathrm{~A}, \mathrm{R} 7 \mathrm{~B}$ | $499 \mathrm{k} \Omega$ | $1.5 \mathrm{M} \Omega$ | R 35 | $2.2 \mathrm{k} \Omega$ | shorted |
| R 7 C | --- | $499 \mathrm{k} \Omega$ | R 36 | $10 \mathrm{k} \Omega$ | $5.6 \mathrm{k} \Omega$ |
| R 15 | $10 \mathrm{k} \Omega$ | $15 \mathrm{k} \Omega$ | R C | --- | $7.5 \mathrm{k} \Omega$ |
| R 16 | $22 \mathrm{k} \Omega$ | $11 \mathrm{k} \Omega$ | C 13 | 15 nF | 3.3 nF |
| R28 | $3.3 \Omega$ | $1 \Omega$ | C 25 | 330 nF | 3.3 nF |
| R29 | $348 \Omega$ | $3.16 \mathrm{k} \Omega$ | C 30 | --- | $33 \mathrm{nF} / 400 \mathrm{~V}$ |
| R30 | $1.2 \mathrm{k} \Omega$ | --- | $\mathrm{D} 13, \mathrm{D} 14$ | -- | 1 N 4148 |

## 80W AC-DC adapter with PFC: evaluation results

The following diagrams compare the performance of the original design ("standard standby") with that of the modified one ("improved standby").
To be noted in figure 14, the no-load consumption is slightly less than $0.5 \mathrm{~W} @ 264 \mathrm{Vac}$, then the modified 80W adapter now meets the ECC limits, Phase 3 for the 15-50W bracket (< 0.5W @230Vac).

Figure 14. 80W AC-DC adapter with PFC: light load input consumption comparison


Figure 15. 80W AC-DC adapter with PFC: $f_{s w}$ vs. $l_{\text {out }}$ (left); $f_{s w}$ vs. $V_{\text {in }}$ (right)


Figure 16. 80W AC-DC adapter with PFC: $P_{\text {in }}\left(@ P_{\text {out }}=0\right)$ and $f_{\text {sw }}$ vs. ambient temperature


The diagrams in figure 15 illustrate the relationship between output current, input voltage and switching frequency obtained with the modified oscillator. Unlike the previously considered design, in this case the internal propagation delay of the current sense pin is not compensated, then VCOMP changes slightly with the input voltage and then there is a variation of the oscillator frequency.
The diagrams of figure 16 illustrate the very limited temperature effect on both the oscillator frequency and the no-load input consumption at both nominal voltages in the temperature range $0-70^{\circ} \mathrm{C}$.
Figure 17. 80W AC-DC adapter with PFC, flyback section: waveforms @ $P_{\text {out }}=80 \mathrm{~W}$


Figure 18. 80W AC-DC adapter with PFC, flyback section: waveforms @P ${ }_{\text {out }}=30 \mathrm{~W}$


Figure 19. 80W AC-DC adapter with PFC, flyback section: waveforms @ $P_{\text {out }}=0.5 \mathrm{~W}$


Figure 20. 80W AC-DC adapter with PFC, flyback section: waveforms @ $P_{\text {out }}=0.3 \mathrm{~W}$


Figure 21. 80W AC-DC adapter with PFC, flyback section: waveforms @ $\mathrm{P}_{\text {out }}=0 \mathrm{~W}$


Figure 22. 80W AC-DC adapter with PFC, flyback section: load transient $0.1 \Leftrightarrow 4.5 \mathrm{~A} @ 220 \mathrm{Vac}$


## Conclusions

A simple modification of the oscillator allows optimizing L5991-based converters to achieve a considerable decrease of the no-load consumption. This has been proved in a 45 W AC-DC adapter and in an 80 W power-factorcorrected adapter, where the optimization here proposed has brought a reduction of the no-load input consumption up to 400 mW at high line.
This is the result of concurrent improvements. The modification to the oscillator allows very low switching frequency under no-load conditions without a large $\mathrm{f}_{\text {osc }}$ to fsB ratio. The resulting lower $\mathrm{V}_{\text {Comp }}$ jump provides more headroom for overshoots and undershoots, so that it has been possible to enlarge the bandwidth of the control loop without any frequency instability. In turn, the faster response due to the larger bandwidth has allowed the reduction of the dummy load on the output, without compromising correct start-up when the adapter is unloaded. The lower residual load and the loss reduction due to the very low oscillator frequency, results in a dramatic decrease of the power absorbed from the mains at no load.

## REFERENCES

[1] "L5991/L5991A Primary Controller with Standby" Datasheet
[2] "Minimize Power Losses of Lightly Loaded Flyback Converters with the L5991 PWM Controller" (AN1049)
[3] "45W AC-DC Adapter with Standby Function" (AN1134)
[4] "80W Power-factor-corrected AC-DC Adapter with Standby Using the L6561 and the L5991A" (AN1440)

## APPENDIX

## How to calculate $\mathbf{R}_{\mathrm{C}}$ and $\mathrm{R}^{\prime}$.

As previously said in the section "Standby function improvement", there is no change for the calculation of the timing components $\mathrm{C}_{\mathrm{T}}, \mathrm{R}_{\mathrm{A}}, \mathrm{R}_{\mathrm{B}}$ because $\mathrm{R}_{\mathrm{C}}$ is disconnected by the series diode D 1 when $\mathrm{V}_{\mathrm{COMP}}>3 \mathrm{~V}$. Then only the calculation of $R_{c}$ to get a given $f_{\text {min }}$, as well as that of $R^{\prime}$ needs to be taken into consideration.
To this end it is necessary to consider first the timing equations that govern the operation of the oscillator. Refer to figure A1 for the equivalent circuit and the relevant waveform, which assume that D1 and D2 match.

Figure A1. Equivalent circuit for oscillator calculations (left) and theoretical V(RCT) waveform (right)


As long as the oscillator voltage $V\left(R C T\right.$ ) is less then $V_{C O M P}$, $D 1$ is reverse-biased ( $S W$ is open) and only $R_{A}$ contributes to the time constant $\tau$; moreover, the asymptote of the exponential curve is the reference voltage $\mathrm{V}_{\text {REF }}(5 \mathrm{~V})$. When $\mathrm{V}\left(\mathrm{RCT}\right.$ ) equals and exceeds $\mathrm{V}_{\text {COMP, }} \mathrm{D} 1$ is forward-biased (SW is closed), then Rc goes in parallel to $R_{A}$ to determine the time constant $\tau$ ' and the asymptote will be changed to:

$$
v_{\text {REF }} \frac{R_{C}}{R_{A}+R_{C}}+v_{\text {COMP }} \frac{R_{A}}{R_{A}+R_{C}}<V_{\text {REF }}
$$

Note that the new time constant $\tau^{\prime}$ is shorter, then it will be the lower asymptote the responsible for getting a longer oscillator period. The complete equation describing the oscillator is then
where:

$$
V(R C T)=\left\{\begin{array}{l}
V_{V}+\left(V_{R E F}-V_{V}\right)\left(1-e^{-\frac{t}{\tau}}\right) t \leq T_{1}  \tag{A1}\\
V_{\text {REF }} \frac{R_{C}}{R_{A}+R_{C}}+V_{\text {COMP }} \frac{R_{A}}{R_{A}+R_{C}}-\frac{R_{C}}{R_{A}+R_{C}}\left(V_{R E F}-V_{\text {COMP }}\right) e^{-\frac{t-T_{1}}{\tau^{\prime}}} t>T_{1}
\end{array}\right.
$$

$$
T_{1}=\tau \ln \frac{V_{R E F}-V_{V}}{V_{R E F}-V_{\text {COMP }}}=\tau \ln \frac{4}{5-V_{\text {COMP }}}
$$

is the time when $\mathrm{V}(\mathrm{RCT})=\mathrm{V}_{\text {COMP }}$ and $\mathrm{R}_{\mathrm{C}}$ comes into play (i.e. SW is closed), $\mathrm{V}_{V}$ is the oscillator valley voltage (1V) and the time constants $\tau$ and $\tau$ ' are defined as shown in figure A 1 .
To find a simple formula to calculate $R_{c}$ some simplifications are necessary. Usually $T_{1} \ll T_{s w}=1 / f_{\text {min }}$, then $T_{1}$ will be neglected and it is possible to write:

$$
\begin{equation*}
V_{p k}=V_{R E F} \frac{R_{C}}{R_{A}+R_{C}}+V_{C o M P_{0}} \frac{R_{A}}{R_{A}+R_{C}}-\frac{R_{C}}{R_{A}+R_{C}}\left(V_{R E F}-V_{C_{O M P}}\right) e^{-\frac{T_{s w}}{\tau^{\prime}}} \tag{A2}
\end{equation*}
$$

where $\mathrm{V}_{\mathrm{pk}}$ is the oscillator peak voltage ( 3 V ) and $\mathrm{V}_{\text {COMPo }}$ the value of $\mathrm{V}_{\text {COMP }}$ under no-load conditions. But, if $\mathrm{T}_{1} \ll \mathrm{~T}_{\text {sw }}$ it will be also $\tau^{\prime} \ll \mathrm{T}_{\text {sw }}$ and the exponential term in (A2) can be neglected. Then (A2) becomes:

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$$
V_{p k}=V_{R E F} \frac{R_{C}}{R_{A}+R_{C}}+V_{\text {COMP }} \frac{R_{A}}{R_{A}+R_{C}}
$$

that, solved for RC, yields:

$$
\begin{equation*}
R_{C}=R_{A} \frac{V_{\text {pk }}-V_{\text {COMP }_{0}}}{V_{\text {REF }}-V_{p k}}=R_{A} \frac{3-V_{\text {COMP }_{0}}}{2} . \tag{A3}
\end{equation*}
$$

The maximum value for R' can be calculated by imposing that D2 be always forward-biased, that is its current never fall to zero, with $\mathrm{V}_{\text {COMP }}=\mathrm{V}_{\text {Compo }}$. The current flowing through D2 is:

$$
I_{D 2}=\frac{V_{C O M P_{0}}-V_{F}}{R^{\prime}} I_{D 1} \text {, }
$$

while the maximum current flowing through D1 is:

$$
\left.\mathrm{I}_{\mathrm{D} 1 \mathrm{x}}=\frac{\mathrm{V}_{\mathrm{pk}}-\mathrm{V}_{\mathrm{F}}-\left(\mathrm{V}_{\mathrm{COMP}}^{0}\right.}{}-\mathrm{V}_{\mathrm{F}}\right) \mathrm{R}_{\mathrm{C}}-=\frac{\mathrm{V}_{\mathrm{pk}}-\mathrm{V}_{\mathrm{COMP}}^{0}}{} R_{\mathrm{C}}=\frac{3-\mathrm{V}_{\mathrm{COMP}}^{0}}{} .
$$

Then, imposing $\mathrm{I}_{\mathrm{D} 2}>0$ with $\mathrm{I}_{\mathrm{D} 1}=\mathrm{I}_{\mathrm{D} 1 \mathrm{x}}$ and solving for $\mathrm{R}^{\prime}$, it is possible to obtain:

$$
\begin{equation*}
\mathrm{R}^{\prime}<\mathrm{R}_{\mathrm{C}} \frac{\mathrm{~V}_{\mathrm{COMP}_{0}}-\mathrm{V}_{\mathrm{F}}}{\mathrm{~V}_{\mathrm{pk}}-\mathrm{V}_{\mathrm{COMP}}}=\mathrm{R}_{\mathrm{C}} \frac{\mathrm{~V}_{\mathrm{COMP}}-\mathrm{V}_{\mathrm{F}}}{3-\mathrm{V}_{\mathrm{COMP}}} \tag{A4}
\end{equation*}
$$

Since $\mathrm{I}_{\mathrm{D} 1}$ and $\mathrm{ID}_{\mathrm{D} 2}$ are typically in the hundred $\mu \mathrm{A}$, with good approximation it is possible to assume $\mathrm{V}_{\mathrm{F}}=0.5 \mathrm{~V}$ @ $25^{\circ} \mathrm{C}$ in (A4). Worst-case scenario is at minimum operating temperature: $-2.5 \mathrm{mV} /{ }^{\circ} \mathrm{C}$ drift can be considered to take this into account.
The point is now to calculate the value of $\mathrm{V}_{\text {COMPo. }}$. In [2] it is shown that in L5991-based flyback converters the following relationships holds true:

$$
\begin{equation*}
\mathrm{V}_{\text {COMP }}=1.4+3\left[\operatorname{Rs}\left(\sqrt{\frac{2 \mathrm{P}_{\text {in }}}{\mathrm{f}_{s w} L_{p}}}-\frac{\mathrm{V}_{\text {in }}}{\mathrm{L}_{\mathrm{p}}} T_{\text {delay }}\right)+\mathrm{V}_{0}\right], \tag{A5}
\end{equation*}
$$

where Rs is the sense resistor (R15 in figure 3, R25 in figure 12), Pin the input power to the transformer, $\mathrm{L}_{\mathrm{p}}$ its primary inductance, $V_{\text {in }}$ the DC input voltage to the converter, Tdelay the internal propagation delay of the current sense pin (200 ns typ.) and $\mathrm{V}_{0}$ a DC voltage offset that can be applied to the current sense pin. In case the offset $\mathrm{V}_{0}$ is chosen equal to

$$
\mathrm{Rs} \frac{\mathrm{~V}_{\text {in }}}{\mathrm{L}_{\mathrm{p}}} T_{\text {delay }}
$$

the effect of the propagation delay is compensated and $\mathrm{V}_{\text {COMP }}$ will no longer depend on the input voltage $\mathrm{V}_{\text {in }}$. That is the case of the 45 W adapter, where the job is done by R3 and R4 along with R14. For the 80 W adapter there is no compensation $\left(\mathrm{V}_{\mathrm{O}}=0\right)$ then there will be a slight dependence of $\mathrm{V}_{\text {COMP }}$ (and then of the oscillator frequency when $\mathrm{R}_{\mathrm{c}}$ is active) on $\mathrm{V}_{\text {in }}$. This is confirmed by the experimental results.
Figure A2. $\mathrm{V}_{\text {COMP }}$ voltage under no-load conditions: 45 W adapter (left), 80W adapter (right)


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To calculate $\mathrm{V}_{\mathrm{COMPO}}$, $\mathrm{P}_{\text {in }}$ needs to be estimated considering the power processed by the transformer under noload conditions. It is possible to use the following formula:

$$
\begin{equation*}
\mathrm{P}_{\text {in }}=1.25\left(\mathrm{~V}_{\text {out }} l_{\text {outres }}+\mathrm{V}_{\text {aux }} l_{\text {aux }}\right) \tag{A6}
\end{equation*}
$$

where $I_{\text {outres }}$ is the residual output current (through the output divider, through the optocoupler's LED, as well as any residual dummy load resistor), Vaux is the voltage generated by the auxiliary winding that supplies the L5991 (and the L6561 in the 80W adapter) and laux the total consumption on this winding (quiescent current of the L5991, of the L6561 too in the 80W adapter, optocoupler's transistor current and the consumption of any circuit supplied by the reference voltage of the L5991 or directly connected to its supply bus). The coefficient 1.25 stems from an estimated efficiency of $80 \%$ that experiments have shown many flyback transformers feature under no-load conditions, almost regardless of their size, parameters and construction.
It is obvious that the estimate of $\mathrm{P}_{\mathrm{in}}$ is the weak point of this design procedure. Since it is essentially the asymptote of the oscillator waveform that governs the oscillator frequency, even some ten mV variation of $\mathrm{V}_{\mathrm{COMPO}}$ may change the frequency considerably. A small error in the assessment of $\mathrm{V}_{\text {COMPo, }}$, then, could lead to a value for $R_{c}$ that gives an $f_{m i n}$ away from the target. This is why it is recommended to use the result of the calculation as a starting point that has to be checked on the bench and, in case, corrected after the experiments. For completeness, it must be said also that under no-load conditions $\mathrm{V}_{\text {COMP }}$ is far from being a perfect DC voltage, as shown in the diagrams of figure A2.

## 45W adapter example calculation

With $C_{T}=3.3 \mathrm{nF}$, $R_{A}$ and $R_{B}$ are $12 \mathrm{k} \Omega$ each. The residual output load is 40 mW , the total consumption of the auxiliary winding is estimated around $l_{\mathrm{aux}}=10 \mathrm{~mA}$, that is 110 mW assuming $\mathrm{V}_{\mathrm{aux}}=11 \mathrm{~V}$. Then, using (A6):

$$
P_{\text {in }} \approx 1.25(0.04+0.11)=0.188 \mathrm{~W}
$$

$V_{\text {COMPO }}$ will be given by (A5), where it is assumed a perfect propagation delay compensation:

$$
\mathrm{V}_{\mathrm{COMP}_{0}}=1.4+3 \cdot 0.47 \sqrt{\frac{2 \cdot 0.188}{5 \cdot 10^{3} \cdot 400 \cdot 10^{-6}}}=2.011 \mathrm{~V}
$$

From (A3):

$$
R_{C}=12 \cdot 10^{3} \frac{3-2.011}{2}=5.934 \cdot 10^{3} \text { use standard value } 5.9 \mathrm{k} \Omega \text {. }
$$

From (A4), considering $\mathrm{T}_{\mathrm{amb}}=0^{\circ} \mathrm{C}$, then $\mathrm{V}_{\mathrm{F}}=0.563 \mathrm{~V}$ :

$$
R^{\prime}<5.9 \cdot 10^{3} \frac{2.011-0.563}{3-2.011}=8.638 \cdot 10^{3} \text { use standard value } 8.2 \mathrm{k} \Omega
$$

## 80W adapter example calculation

With $\mathrm{C}_{\top}=3.3 \mathrm{nF}$, we get $\mathrm{R}_{\mathrm{A}}=15 \mathrm{k} \Omega$ and $\mathrm{R}_{\mathrm{B}}=11 \mathrm{k} \Omega$. The residual output load is 40 mW , the total estimated consumption of the auxiliary winding is laux $=12 \mathrm{~mA}$, that is 120 mW assuming $\mathrm{V}_{\mathrm{aux}}=10 \mathrm{~V}$. Then, using (A6):

$$
P_{\text {in }} \approx 1.25(0.04+012)=0.2 \mathrm{~W}
$$

$\mathrm{V}_{\text {COMPO }}$ will be given by (A5):

$$
\mathrm{V}_{\mathrm{COMP}_{0}}=1.4+3 \cdot 0.28\left(\sqrt{\frac{2 \cdot 0.2}{5 \cdot 10^{3} \cdot 430 \cdot 10^{-6}}}-\frac{375 \cdot 200 \cdot 10^{-9}}{430 \cdot 10^{-6}}\right)=1.616 \mathrm{~V}
$$

From (A3):

$$
\mathrm{R}_{\mathrm{C}}=11 \cdot 10^{3} \frac{3-1.616}{2}=7.612 \cdot 10^{3} \text { use standard value } 7.5 \mathrm{k} \Omega
$$

From (A4) ), considering $\mathrm{T}_{\mathrm{amb}}=0^{\circ} \mathrm{C}$, then $\mathrm{V}_{\mathrm{F}}=0.563 \mathrm{~V}$ :

$$
R^{\prime}<7.5 \cdot 10^{3} \cdot \frac{1.616-0.563}{3-1.616}=5.706 \cdot 10^{3} \text { use standard value } 5.6 \mathrm{k} \Omega .
$$

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